

| Technical Data | SGA24, SGF24 |
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| Power supply | 24 VAC $\pm 20 \% 50 / 60 \mathrm{~Hz}, 24 \mathrm{VDC} \pm 10 \%$ |
| Transformer sizing | 1 VA |
| Control signal Y | 0.5 to 10 VDC; 2 to 10 VDC (switchable) |
| Power output | up to 10 actuators (1 mA max) |
| Degree of protection | (SGA24 only NEMA 2 [IP54]) |
| Connection | Terminals (14 ga. wire max) |
| Humidity | 5 to $95 \%$ RH non-condensing |

## Wiring Diagrams



Minimum Position Setting

$\triangle$
Provide overload protection and disconnect as required.
Override switches are optional.
3. A $500 \Omega$ resistor (ZG-R01) must be added for 4 to 20 mA control.

## Application

These positioners are intended for the remote control of modulating actuators or for use as a minimum positioner (providing a minimum limit for the output signal from a modulating controller). The control range is 0 to $100 \%$ of the angle of rotation of the actuator.

Positioner SGA24 is for surface mounting with a NEMA 2 housing included. Positioner SGF24 is for flush mounting.

## Operation

The positioner receives its supply voltage through terminals 1 and 2 . A rotary knob is turned, producing a proportional control signal $(\mathrm{Y})$ at the output (terminal 3 ) of either 0.5 to 10 VDC or 2 to 10 VDC and therefore a proportional change in the position of the actuator between 0 and 100\%. When used for a minimum limit, the positioner works as a higher of 2 signal selector. This function allows only the signal from the controller or positioner, whichever is greater, to go to the actuator.

## Function

The changeover from 2 to 10 V to 0 to 10 V is selected by means of a slide switch on the printed circuit board.

The angle of rotation of the knob can be limited mechanically, by moving the adjustable stops under the knob.

## Accessory



Drilling template for SGF24 (flush mount)


